

Measuring Association/Predictive power on Topological Spaces Using Kernels and Graphs

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<https://arxiv.org/pdf/2010.01768.pdf>

<https://arxiv.org/pdf/2012.14804.pdf>

Formal Introduction: Pearson's Correlation and beyond?

- $(X, Y) \sim \mu$ on $\mathcal{X} \times \mathcal{Y}$ (topological spaces) with marginals μ_X, μ_Y
- **Informal goal:** Construct a **measure** that can capture the **strength of association** between X and Y

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What are truly **nonparametric analogs** of the **Pearson's correlation**?

Think of nonparametric regression

- This asymmetry is fundamental in even simple regression problems, consider the noiseless version:

$$Y = f(X).$$

- If $f(\cdot)$ is a **many-to-one** function, predicting X from Y is not possible whereas predicting Y from X is immediate irrespective of $f(\cdot)$.
- Pearson's correlation being symmetric cannot distinguish between the two problems — same is the case for most **measures of dependence**.
- Design a **directional** measure that
 - 1 is **“small”** for “predicting” X from Y .
 - 2 but **large** for “predicting” Y from X .

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- **Want** a measure that equals 0 iff $X \perp\!\!\!\perp Y$, equals 1 iff Y is “some function” of X .
- For the past century, most measures of association/dependence only focus on **testing for independence**, i.e., they equal 0 iff $Y \perp\!\!\!\perp X$; e.g., **distance correlation** (Székely et al., 2007), Hilbert-Schmidt independence criterion (Gretton et al., 2008), graph-based measures (Friedman and Rafsky, 1983), etc.

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Recent advances

- In Dette et al., 2013, Chatterjee, 2019. When $\mathcal{X} = \mathcal{Y} = \mathbb{R}$, authors propose measures that equal 0 iff $Y \perp\!\!\!\perp X$ and 1 iff Y is a **measurable function** of X . Extended to the case $\mathcal{X} = \mathbb{R}^{d_1}$ and $\mathcal{Y} = \mathbb{R}$ in Azadkia and Chatterjee, 2019.

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- 1 A family of measures of association
 - A measure on $\mathcal{X} = \mathbb{R}^{d_1}$, $\mathcal{Y} = \mathbb{R}^{d_2}$
 - Interpretability and monotonicity
 - Extending to a class of kernel measures

- 2 Estimating the kernel measure
 - Proposing the estimator
 - Computational complexity
 - Consistency
 - Rate of estimation
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Basic strategy

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- Most measures of dependence quantify a “discrepancy” between μ and $\mu_X \otimes \mu_Y$.
- We construct a discrepancy between $\mu_{Y|X}$ (regular conditional distribution) and μ_Y .
- When $Y \perp\!\!\!\perp X$, $\mu_{Y|X} = \mu_Y$. When Y is a measurable function of X , $\mu_{Y|X}$ is a **degenerate measure**.
- Define

$$T \equiv T(\mu) := 1 - \frac{\mathbb{E}\|Y' - \tilde{Y}'\|_2}{\mathbb{E}\|Y_1 - Y_2\|_2}.$$

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- Generate $Y_1, Y_2 \stackrel{i.i.d.}{\sim} \mu_Y$.
- (X', Y', \tilde{Y}') is generated as: draw $X' \sim \mu_X$ and then $Y'|X' \sim \mu_{Y|X'}$, $\tilde{Y}'|X' \sim \mu_{Y|X'}$ such that Y' and \tilde{Y}' are conditionally independent given X' .

Some intuition

- Suppose $d_2 = 1$.
- Consider a slight modification:

$$T^* \equiv T^*(\mu) := 1 - \frac{\mathbb{E}|Y' - \tilde{Y}'|^2}{\mathbb{E}|Y_1 - Y_2|^2}.$$

- Plug-in $\mathbb{E}|Y' - \tilde{Y}'|^2 = \mathbb{E}|Y'|^2 + \mathbb{E}|\tilde{Y}'|^2 - 2\mathbb{E}Y'\tilde{Y}'$.
- Do the same for the denominator.
- Simplify $T^*(\mu)$ to get:

$$T^*(\mu) = \frac{\text{Var}(\mathbb{E}[Y|X])}{\text{Var}(Y)} \in [0, 1].$$

- T can be interpreted as the **proportion of the variance of Y explained by X** .

Back to $T(\mu)$ — More intuition

- Recall $X' \sim \mu_X$ and $Y'|X' \sim \mu_{Y|X'}$, $\tilde{Y}'|X' \sim \mu_{Y|X'}$ such that Y' and \tilde{Y}' are conditionally independent given X' .

$$T = 1 - \frac{\mathbb{E}\|Y' - \tilde{Y}'\|_2}{\mathbb{E}\|Y_1 - Y_2\|_2}.$$

$Y' \sim \mu_Y$, $\tilde{Y}' \sim \mu_Y$ but Y' and \tilde{Y}' are **not independent**.

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$$\mu_{Y|X'} = \mu_Y, Y', \tilde{Y}' \stackrel{i.i.d.}{\sim} \mu_Y$$

and so $T = 0$.

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- Suppose $Y = h(X)$ for some measurable $h(\cdot)$, then

$$Y' = \tilde{Y}' = h(X'), \quad \|Y' - \tilde{Y}'\|_2 = 0$$

and so $T = 1$.

A formal result

Theorem

Suppose $\mathbb{E}\|Y_1\|_2 < \infty$. Then

- $T \in [0, 1]$.
- $T = 0$ iff $Y \perp\!\!\!\perp X$.
- $T = 1$ iff Y is a noiseless measurable function of X .

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- $T \in [0, 1]$.
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- The choice $\|\cdot\|_2$ is important. For instance,

$$1 - \frac{\mathbb{E}\|Y' - \tilde{Y}'\|_2^2}{\mathbb{E}\|Y_1 - Y_2\|_2^2}$$

can be 0 even when $Y \not\perp\!\!\!\perp X$.

Monotonicity

What happens in the interval $(0, 1)$?

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T for bivariate normal

Suppose μ is the bivariate normal distribution with means μ_X, μ_Y , variances σ_X^2, σ_Y^2 and correlation ρ . Then

$$T(\mu) = 1 - \sqrt{1 - \rho^2}.$$

The above function is **strictly convex and increasing** in $|\rho|$.

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Other examples: Let

$$Y = \lambda g(X) + \epsilon$$

where $\lambda \geq 0$, ϵ, X are independent, $\epsilon' \stackrel{i.i.d.}{\sim} \epsilon$ such that $\epsilon - \epsilon'$ is unimodal. Then $T(\mu)$ is monotonic in λ .

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In nonparametric regression models with additive noise, T turns out to be a **monotonic** function of the **noise variance**.

Preliminaries: reproducing kernel Hilbert spaces (RKHS)

- RKHS on \mathcal{Y} : **linear, complete, inner product** space of functions from $\mathcal{Y} \rightarrow \mathbb{R}$; non-negative definite **kernel**; “reproducing property”.
- Consider a non-negative definite **kernel function** on \mathcal{Y} — $K : \mathcal{Y} \times \mathcal{Y} \rightarrow \mathbb{R}$ satisfying

$$\sum_{i,j=1}^m \alpha_i \alpha_j K(y_i, y_j) \geq 0$$

for all $\alpha_i \in \mathbb{R}$, $y_i \in \mathcal{Y}$ and $m \geq 1$.

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for all $\alpha_i \in \mathbb{R}$, $y_i \in \mathcal{Y}$ and $m \geq 1$.

- Note $K(y, \cdot) : \mathcal{Y} \rightarrow \mathbb{R}$.
- Identify $y \mapsto K(y, \cdot)$ (feature map).
- (**Reproducing property**) For all $f \in \mathcal{H}$, $y \in \mathcal{Y}$, $\langle f, K(y, \cdot) \rangle_{\mathcal{H}} = f(y)$.

RKHS (continued) - useful identities

As a consequence of the reproducing property:

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- Using the above,

$$\begin{aligned} & \|K(y_1, \cdot) - K(y_2, \cdot)\|_{\mathcal{H}}^2 \\ &= \langle K(y_1, \cdot), K(y_1, \cdot) \rangle_{\mathcal{H}} + \langle K(y_2, \cdot), K(y_2, \cdot) \rangle_{\mathcal{H}} - 2\langle K(y_1, \cdot), K(y_2, \cdot) \rangle_{\mathcal{H}} \\ &= K(y_1, y_1) + K(y_2, y_2) - 2K(y_1, y_2). \end{aligned}$$

Kernel measure of association (KMAc)

- Recall $K(y, \cdot) : \mathcal{Y} \rightarrow \mathbb{R}$ for all $y \in \mathcal{Y}$, y identified with $K(y, \cdot)$ and

$$T = 1 - \frac{\mathbb{E} \|Y' - \tilde{Y}'\|_2}{\mathbb{E} \|Y_1 - Y_2\|_2}.$$

- Replace $Y_1 - Y_2$ with $K(Y_1, \cdot) - K(Y_2, \cdot)$.

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- Replace $\|Y_1 - Y_2\|_2$ with $\|K(Y_1, \cdot) - K(Y_2, \cdot)\|_{\mathcal{H}}^2$.
- Define

$$\eta_K := 1 - \frac{\mathbb{E} \|K(Y', \cdot) - K(\tilde{Y}', \cdot)\|_{\mathcal{H}}^2}{\mathbb{E} \|K(Y_1, \cdot) - K(Y_2, \cdot)\|_{\mathcal{H}}^2}$$

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Theorem (informal)

Suppose $K(\cdot, \cdot)$ is **characteristic** and $\mathbb{E}K(Y_1, Y_1) < \infty$, then:

- $\eta_K \in [0, 1]$.
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- A kernel is **characteristic** if

$$\mathbb{E}_P[K(Y, \cdot)] = \mathbb{E}_Q[K(Y, \cdot)] \implies P = Q$$

for probability measures P and Q .

Examples

Characteristic kernels — [Gretton et al., 2012](#), [Sejdinovic et al., 2013](#), [Lyons 2013, 2014](#). Some examples include:

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$$\eta_K = T.$$

- Bounded kernels: (Gaussian) $K(y_1, y_2) := \exp(-\|y_1 - y_2\|_2^2)$ and (Laplacian) $K(y_1, y_2) := \exp(-\|y_1 - y_2\|_1)$.
- For **non-Euclidean domains** such as video filtering, robotics, text documents, human action recognition, characteristic kernels constructed in [Fukumizu et al., 2009](#), [Danafar et al., 2010](#), [Christmann and Steinwart, 2010](#).

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Estimation strategy

- Suppose $(X_1, Y_1), \dots, (X_n, Y_n) \sim \mu$.
- \mathcal{X} is endowed with metric $\rho_{\mathcal{X}}(\cdot, \cdot)$.

- Recall

$$\eta_K = \frac{\mathbb{E}K(Y', \tilde{Y}') - \mathbb{E}K(Y_1, Y_2)}{\mathbb{E}K(Y_1, Y_1) - \mathbb{E}K(Y_1, Y_2)}.$$

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- From standard U-Statistic theory,

$$\mathbb{E}K(Y_1, Y_1) \approx \frac{1}{n} \sum_{i=1}^n K(Y_i, Y_i)$$

and

$$\frac{1}{n} \sum_{i=1}^n K(Y_i, Y_{i+1}) \approx \mathbb{E}K(Y_1, Y_2) \approx \frac{1}{n(n-1)} \sum_{i \neq j} K(Y_i, Y_j).$$

- Hardest term to estimate is $\mathbb{E}K(Y', \tilde{Y}')$.

Estimation (continued)

- Suppose X is supported on a finite set. A natural estimator

$$\mathbb{E}[\mathbb{E}[K(Y', \tilde{Y}')|X']] \approx \frac{1}{n} \sum_{i=1}^n \frac{1}{|\{j : X_j = X_i\}|} \sum_{j: X_j = X_i} K(Y_i, Y_j).$$

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- If X is continuous, replace $X_j = X_i$ with $\rho_X(X_i, X_j)$ being “small”.
- Construct a graph G_n on $\{X_1, \dots, X_n\}$ which joins points that are “close” to each other.
- For example, consider a **k -nearest neighbor graph (k -NNG)** - join every point to its first k nearest neighbors.

Estimation (continued)

- Replace

$$\frac{1}{n} \sum_{i=1}^n \frac{1}{|\{j : X_j = X_i\}|} \sum_{j: X_j = X_i} K(Y_i, Y_j)$$

with

$$\frac{1}{n} \sum_{i=1}^n \frac{1}{d_i} \sum_{j:(i,j) \in E(G_n)} K(Y_i, Y_j)$$

where $E(G_n)$ — edge/neighbor set of G_n and d_i — degree of X_i .

Estimation (continued)

- Replace

$$\frac{1}{n} \sum_{i=1}^n \frac{1}{|\{j : X_j = X_i\}|} \sum_{j: X_j = X_i} K(Y_i, Y_j)$$

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- Define

$$\hat{\eta}_n := \frac{\frac{1}{n} \sum_{i=1}^n \frac{1}{d_i} \sum_{j:(i,j) \in E(G_n)} K(Y_i, Y_j) - \frac{1}{n(n-1)} \sum_{i \neq j} K(Y_i, Y_j)}{\frac{1}{n} \sum_{i=1}^n K(Y_i, Y_i) - \frac{1}{n(n-1)} \sum_{i \neq j} K(Y_i, Y_j)}.$$

$$\hat{\eta}_n^{\text{lin}} := \frac{\frac{1}{n} \sum_{i=1}^n \frac{1}{d_i} \sum_{j:(i,j) \in E(G_n)} K(Y_i, Y_j) - \frac{1}{n} \sum_{i=1}^N K(Y_i, Y_{i+1})}{\frac{1}{n} \sum_{i=1}^n K(Y_i, Y_i) - \frac{1}{n} \sum_{i=1}^N K(Y_i, Y_{i+1})}.$$

Computational complexity

- Suppose G_n is the k -NNG; computed in $\mathcal{O}(kn \log n)$ time.
- Recall

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- $\hat{\eta}_n^{\text{lin}}$ is computable in **near linear time** as opposed to $\hat{\eta}_n$ which may be **quadratic**. In practice, for certain kernels, one may compute $\hat{\eta}_n$ approximately, in near linear time.

Estimation (continued)

Theorem (informal)

Suppose G_n satisfies the “close”-ness condition in the sense that:

$$\frac{\sum_{(i,j) \in E(G_n)} \rho_{\mathcal{X}}(X_i, X_j)}{|E(G_n)|} \xrightarrow{\mathbb{P}} 0$$

and $\mathbb{E}K(Y_1, Y_1)^{2+\epsilon} < \infty$, then

$$\hat{\eta}_n \xrightarrow{\mathbb{P}} \eta_K, \quad \hat{\eta}_n^{\text{lin}} \xrightarrow{\mathbb{P}} \eta_K.$$

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- Under additional moments, convergence happens **almost surely** in μ (**not required** if bounded kernels are used).
- **No smoothness** assumption needed on $\mathbb{E}K[(\cdot, Y)|X]$.

Examples of graphs (Euclidean)

- Minimum spanning trees, k -nearest neighbor graphs - join every point to its first k nearest neighbors.
- For k -NNG, $\hat{\eta}_n$ is consistent provided $k = o(n/\log n)$.

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$$\hat{\eta}_n - \eta_K = \underbrace{(\hat{\eta}_n - \mathbb{E}\hat{\eta}_n)}_{\text{Variance term}} + \underbrace{(\mathbb{E}\hat{\eta}_n - \eta_K)}_{\text{Bias term}}$$

. The bias \uparrow with k . However the variances stabilizes because

$$\frac{1}{n} \sum_{i=1}^n \frac{1}{d_i} \sum_{j:(i,j) \in E(G_n)} K(Y_i, Y_j).$$

- For consistent estimation, a 1-NNG can be chosen (no tuning required).

Rate of estimation (k -NNG)

Theorem (informal)

Suppose $K(\cdot, \cdot)$ is **bounded**, $\mathbb{E}[K(Y, \cdot)|X = x]$ is **Lipschitz** with respect to $\rho_{\mathcal{X}}(\cdot, \cdot)$ and the support of $\mu_{\mathcal{X}}$ has **intrinsic dimension** d_0 . Then

$$\hat{\eta}_n^{\text{lin}} - \eta_K = \begin{cases} \mathcal{O}_{\mathbb{P}}((\sqrt{k/n})(\log n)) & \text{if } d_0 \leq 2, \\ \mathcal{O}_{\mathbb{P}}((k/n)^{1/d_0}(\log n)) & \text{if } d_0 > 2. \end{cases}$$

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- When $Y \perp\!\!\!\perp X$, bias is always 0 and variance improves with k — useful in independence testing.

Limiting null (general graph)

Theorem (informal)

Suppose $\mu = \mu_X \otimes \mu_Y$, then there exists sequences of random variables $V_n = \mathcal{O}_{\mathbb{P}}(1)$ and V_n^{lin} such that

$$\frac{\sqrt{n}\hat{\eta}_n^{\text{lin}}}{V_n^{\text{lin}}} \xrightarrow{d} \mathcal{N}(0, 1), \quad \frac{\sqrt{n}\hat{\eta}_n}{V_n} \xrightarrow{d} \mathcal{N}(0, 1).$$

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- (Proof) Uses U-statistics projection theory and Stein's method on dependency graphs.
- (General) a uniform CLT holds for a suitable class of graphs \mathcal{G}_n , i.e.,

$$\sup_{\mathcal{G}_n \in \mathcal{G}_n} \sup_{x \in \mathbb{R}} |\mathbb{P}(\sqrt{n}\hat{\eta}_n^{\text{lin}} / V_n \leq x) - \Phi(x)| \xrightarrow{n \rightarrow \infty} 0.$$

- Theorem holds for **data driven choices** $\hat{\mathcal{G}}_n$ provided $\mathbb{P}(\hat{\mathcal{G}}_n \in \mathcal{G}_n) \xrightarrow{n \rightarrow \infty} 1$.

Independence testing

- Consider the testing problem:

$$H_0 : \mu = \mu_X \otimes \mu_Y \quad \text{vs} \quad H_1 : \mu \neq \mu_X \otimes \mu_Y.$$

- Recall $\eta_K = 0$ iff $\mu = \mu_X \otimes \mu_Y$, $\eta_K > 0$ otherwise, $\hat{\eta}_n \xrightarrow{\mathbb{P}} \eta_K$.

- A natural test:

$$\text{Reject if } \sqrt{n} \hat{\eta}_n^{\text{lin}} / V_n \geq z_\alpha.$$

- Consistent and maintains level, i.e.,

$$\lim_{n \rightarrow \infty} \mathbb{P}_{H_0}(\text{Reject } H_0) = \alpha, \quad \lim_{n \rightarrow \infty} \mathbb{P}_{H_1}(\text{Reject } H_0) = 1.$$

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- Near linear complexity.

Summary

- **Class of kernel measures of association** (KMAc) when \mathcal{Y} admits a non-negative definite kernel.
- **Class of graph-based**, consistent estimators (\mathcal{X} - metric space) for KMAc without smoothness on the conditional distribution.
- When k -NNG is used, the rate of convergence adapts to the intrinsic dimension of the support $\mu_{\mathcal{X}}$.
- Established a pivotal Gaussian limit uniformly over a class of graphs.
- A linear time estimator + a near linear time test of statistical independence.

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- Established a pivotal Gaussian limit uniformly over a class of graphs.
- A linear time estimator + a near linear time test of statistical independence.
- A wide array of numerical experiments with real and simulated datasets - see <https://arxiv.org/pdf/2012.14804.pdf>.

The End

Simulations (choice of k)

$(X^{(1)}, X^{(2)}, Y^{(1)}, Y^{(2)}) \sim \mu$ supported on \mathbb{R}^4 where
 $(X^{(1)}, Y^{(1)}), (X^{(2)}, Y^{(2)})$ are i.i.d., where

- (W-shaped)

$$Y^{(1)} = |X^{(1)} + 0.5|1(X^{(1)} \leq 0) + |X^{(1)} - 0.5|1(X^{(1)} > 0) + 0.75\lambda\epsilon,$$

$\epsilon \sim \mathcal{N}(0, 1)$ with varying λ .

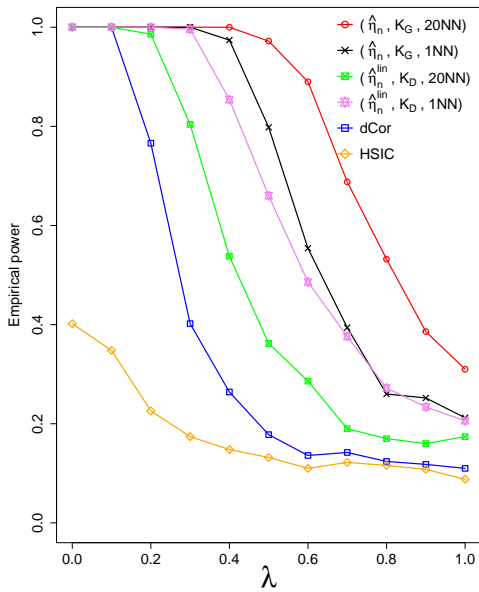
- (Sinusoidal)

$$Y^{(1)} = \cos(8\pi X^{(1)}) + 3\lambda\epsilon,$$

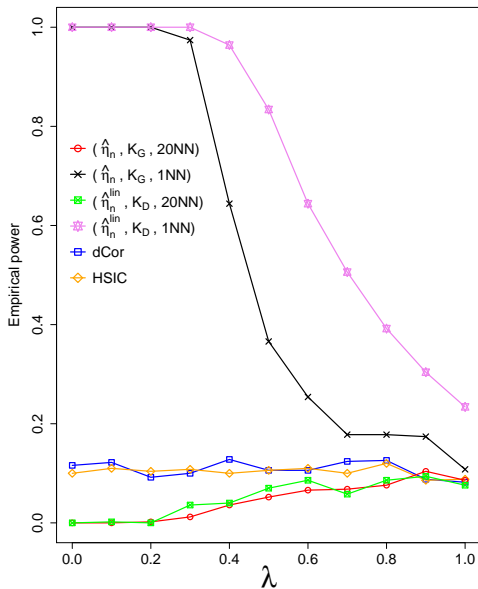
$\epsilon \sim \mathcal{N}(0, 1)$ with varying λ .

Sample size $n = 300$.

W-shaped (K_G -Gaussian kernel, K_D -Distance kernel)



Sinusoidal (K_G -Gaussian kernel, K_D -Distance kernel)



Conditional association

- Recall

$$\eta_K = \frac{\underbrace{\mathbb{E}K(Y', \tilde{Y}')}_{*\mu_{Y|X}} - \underbrace{\mathbb{E}K(Y_1, Y_2)}_{*\mu_Y}}{\mathbb{E}K(Y_1, Y_1) - \mathbb{E}K(Y_1, Y_2)}$$

where $X' \sim \mu_X$, Y', \tilde{Y}' are drawn independently from $\mu_{Y|X'}$.

- The surrogate in the numerator show we are comparing $\mu_{Y|X}$ with μ_Y .

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- The surrogate in the numerator show we are comparing $\mu_{Y|X}$ with μ_Y .
- For conditional association, i.e., **how closely is Y associated with Z given X** , define:

$$\tilde{\eta}_K := \frac{\underbrace{\mathbb{E}K(Y'_2, \tilde{Y}'_2)}_{*\mu_{Y|X,Z}} - \underbrace{\mathbb{E}K(Y', \tilde{Y}')}_{*\mu_{Y|X}}}{\mathbb{E}K(Y_1, Y_1) - \mathbb{E}K(Y', \tilde{Y}'_2)}$$

where $(X', Z') \sim \mu_{XZ}$ and Y'_2, \tilde{Y}'_2 are drawn independently from $\mu_{Y|(X', Z')}$.

Estimating Conditional association

- Recall

$$T_{1,n} := \frac{1}{n} \sum_{i=1}^n \frac{1}{d_i} \sum_{j:(i,j) \in E(G_n)} K(Y_i, Y_j) \approx \mathbb{E}K(Y', \tilde{Y}')$$

where $E(G_n)$ — edge/neighbor set of G_n , the nearest neighbor graph on (X_1, \dots, X_n) and d_i — degree of X_i .

- Use the estimator

$$\hat{\eta}_K := \frac{\frac{1}{n} \sum_{i=1}^n \frac{1}{\tilde{d}_i} \sum_{j:(i,j) \in E(\tilde{G}_n)} K(Y_i, Y_j) - T_{1,n}}{\frac{1}{n} \sum_{i=1}^n K(Y_i, Y_i) - T_{1,n}},$$

\tilde{G}_n — edge/neighbor set of G_n , the nearest neighbor graph on $(X_1, Z_1), \dots, (X_n, Z_n)$ and \tilde{d}_i — degree of (X_i, Z_i) .

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- Then

$$\hat{\eta}_K \xrightarrow{P} \tilde{\eta}_K.$$

Also $\tilde{\eta}_K \in [0, 1]$ and $\tilde{\eta}_K = 0$ iff $Y \perp\!\!\!\perp Z|X$ and $\tilde{\eta}_K = 1$ if Y is a measurable function of X, Z .

Local power in independence testing

- Consider the family of alternatives (Farlie):

$$f_{X,Y}(x,y) = (1 - r_n)f_1(x)f_2(y) + r_n g(x,y).$$

- What happens to test based on $\hat{\eta}_n^{\text{lin}}$ as $r_n \rightarrow 0$?

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- What happens to test based on $\hat{\eta}_n^{\text{lin}}$ as $r_n \rightarrow 0$?
- For $d_1 \leq 7$, power converges to 1 if $r_n \gg n^{-1/4}$ and to 0 if $r_n \ll n^{-1/4}$.
- (Blessing of dimensionality?): For $d_1 \geq 9$, power converges to 1 if $r_n \gg n^{-\left(\frac{1}{2} - \frac{2}{d_1}\right)}$ and power converges to 0 if $r_n \ll n^{-\left(\frac{1}{2} - \frac{2}{d_1}\right)}$.
- For $d = 8$, the power depends on a rather complicated tradeoff.

Illustration of monotonicity

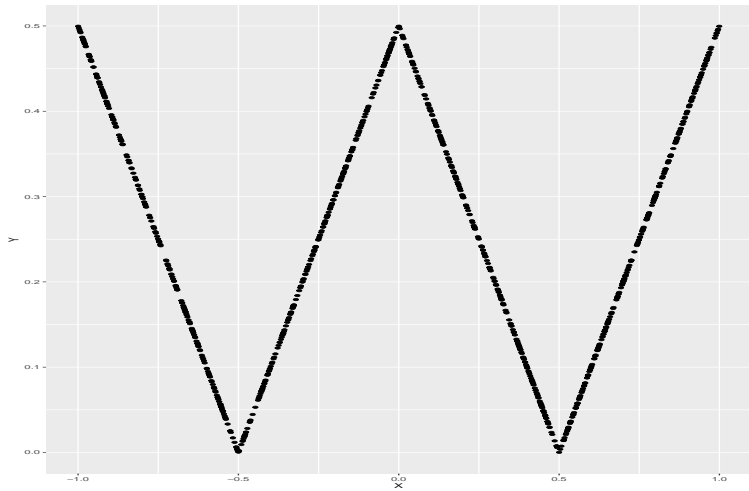
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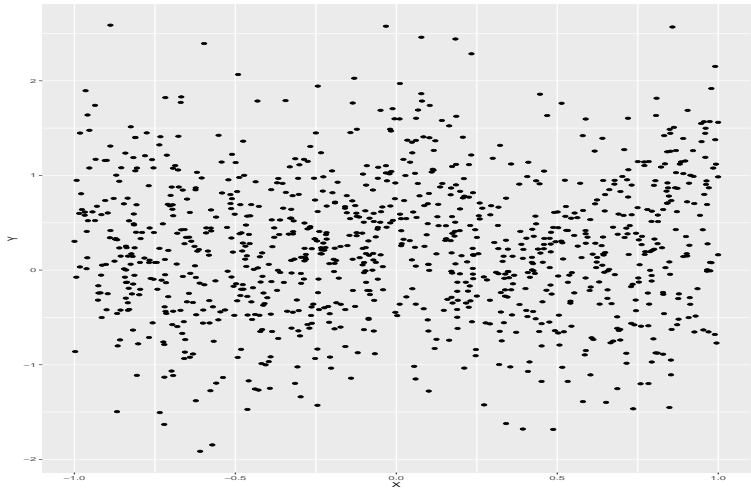
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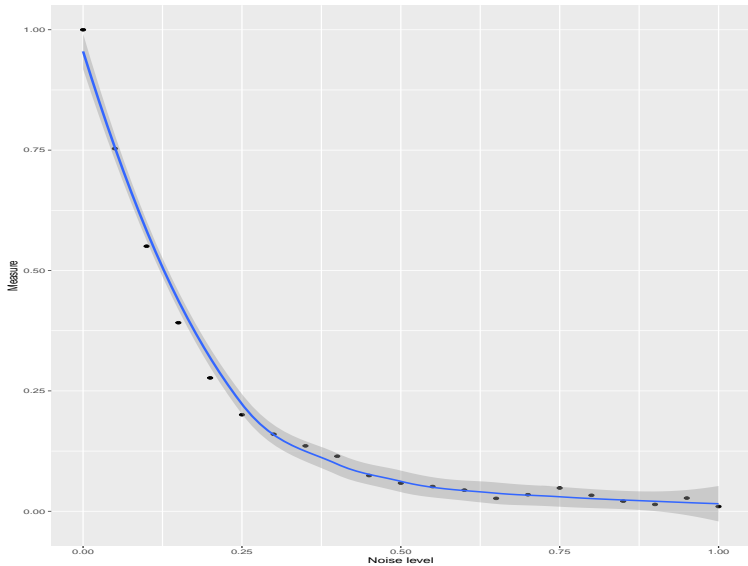
W-shaped (noiseless)



W-shaped (noisy)

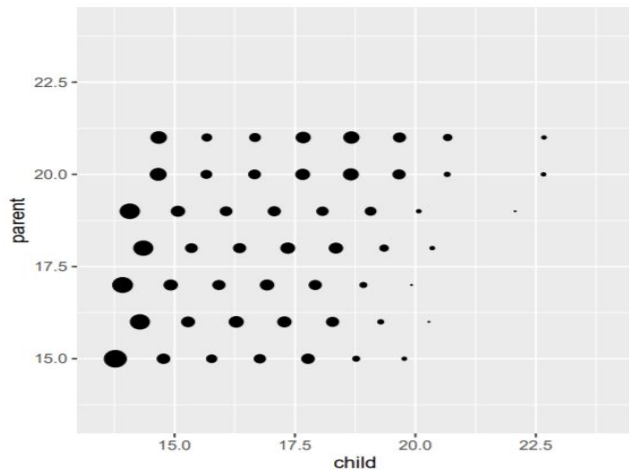


W-shaped (monotonicity)



Galton Peas dataset

- Mean diameters of sweet peas in mother plants and daughter plants (700×2)



Galton Peas (continued)

- 7 unique values for the mother (X) and 52 for the daughter (Y).
- X and Y seem to be **associated**.
- Pearson's correlation = 0.35, p -value \ll 0.05.

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- X and Y seem to be **associated**.
- Pearson's correlation = 0.35, p -value $\ll 0.05$.
- Can we say something more?

A curious observation (Chatterjee, 2020)

Child	Parent						
	15	16	17	18	19	20	21
13.77	46	0	0	0	0	0	0
13.92	0	0	37	0	0	0	0
14.07	0	0	0	0	35	0	0
14.28	0	34	0	0	0	0	0
14.35	0	0	0	34	0	0	0
14.66	0	0	0	0	0	23	0
14.67	0	0	0	0	0	0	22
14.77	14	0	0	0	0	0	0
14.92	0	0	16	0	0	0	0
15.07	0	0	0	0	16	0	0
15.28	0	15	0	0	0	0	0
15.35	0	0	0	12	0	0	0
15.66	0	0	0	0	0	10	0
15.67	0	0	0	0	0	0	8
15.77	9	0	0	0	0	0	0
15.92	0	0	13	0	0	0	0
16.07	0	0	0	0	12	0	0
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- Every row has **exactly one** non-zero element.

Galton Peas (continued)

- Recall X -mother, Y -daughter.
- It is more convenient to predict X from Y (Parent from daughter) than the other way round.
- Pearson's correlation being symmetric cannot distinguish between the two problems — same is the case for most **measures of dependence**.

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- It is more convenient to predict X from Y (Parent from daughter) than the other way round.
- Pearson's correlation being symmetric cannot distinguish between the two problems — same is the case for most **measures of dependence**.
- How to design a measure that captures this asymmetry?